sim4dhs

an algorithm to simulate tree and meshed district heating networks dynamically

presented by Johannes Pelda



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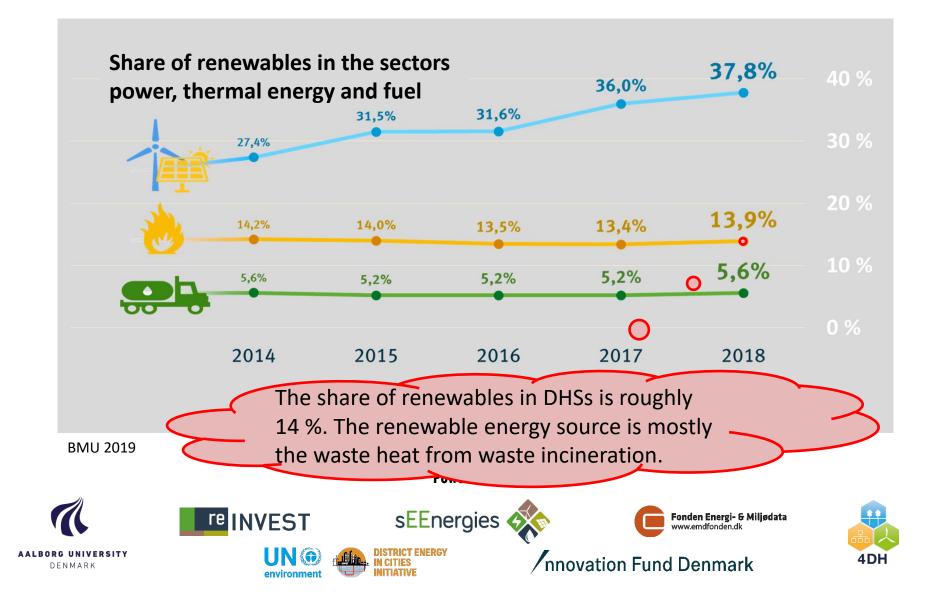


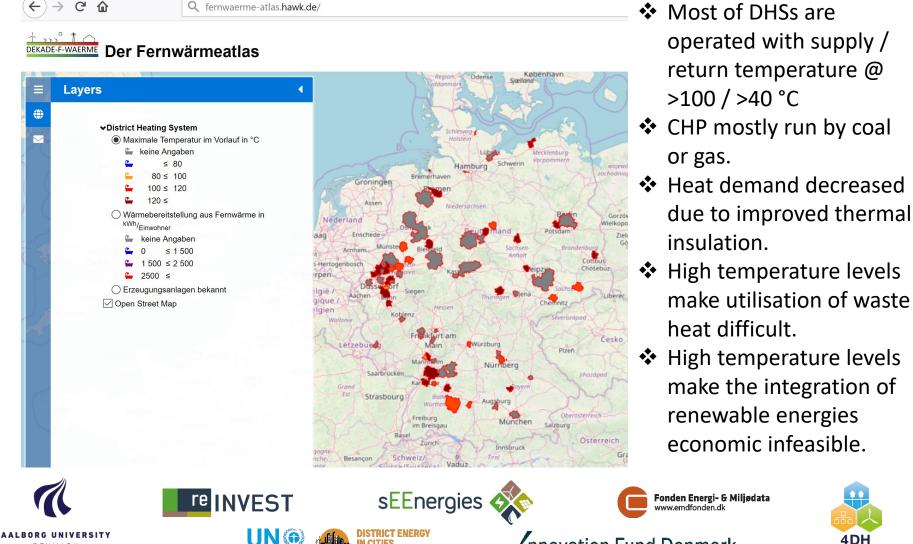


- 1. Introduction
- Hydraulic Load factor 2.
- 3. Methodology
- Example networks 4.
- Outlook 5.



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Targets:

- 1. Examine thermo-hydraulic restrictions occurring while lowering DHSs operating temperatures.
- 2. Compare restrictions with restrictions of today's operational mode.
- 3. Quantify and qualify impact of thermo-hydraulic restrictions using hydraulic load factor

•
$$f_{hlf} = \frac{V_{operation}}{\dot{V}_{max}}$$
 (Equ. 1)

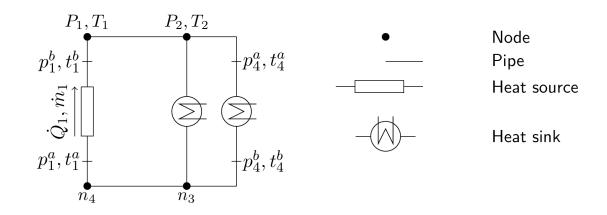
•
$$f_{HLF} = \frac{The \ sum \ of \ the \ length \ of \ pipes \ where \ f_{hlf} > 1}{Overall \ district \ heating \ network \ length}$$
 (Equ. 2

Elaborate on actions to bridge thermo-hydraulic restrictions:

Measures help to bridge thermo-hydraulic restrictions, such as:

- Decentralised heat sources (heat boosters)	- Demand-side-management
- Centralised or decentralised heat storages	- Reduction of return temperature





Small example DHS with inscribed variables for pressure (P, p^a, p^b) , temperature (T, t^a, t^b) , heat-flow (\dot{Q}) and mass flow (\dot{m}) ; For clear view some variables are not inscribed.

1st Kirchhoff's theorem

$0 = \underline{I}_{(n-1,e)} \cdot \overrightarrow{\dot{m}}$ $0 = \begin{pmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,e} \\ a_{2,1} & \ddots & \cdots & \vdots \\ \vdots & \vdots & a_{i,j} & \vdots \\ a_{n-1,1} & \cdots & \cdots & a_{n-1,e} \end{pmatrix} \cdot \begin{pmatrix} \dot{m}_1 \\ \dot{m}_2 \\ \vdots \\ \dot{m}_e \end{pmatrix}$

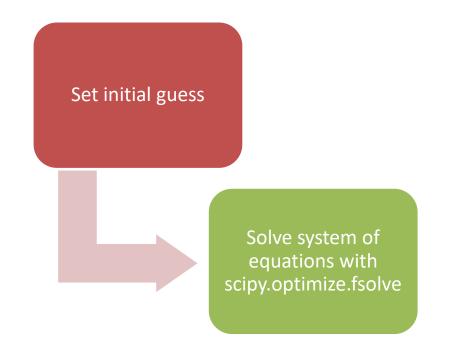
Constitutive relations

Edges	Dependencies	Equations
All edges	thermal	$0 = \dot{m}_i \cdot c_p \cdot \left(t_i^a - t_i^b \right) + \dot{Q}_i$
Straight pipe	thermal	$0 = (kA)_i \cdot \left(\bar{t}_i^{a,b} - t^{amb}\right) + \dot{Q}_i$
	hydraulic	$0 = \left(p_i^a - p_i^b\right) - \frac{8 \cdot \lambda_i \cdot l_i}{\rho \cdot \pi^2 \cdot d^5} \cdot \dot{m}_i \cdot \dot{m}_i + \varrho \cdot g \cdot \left(h_i^a - h_i^a\right)$
Heat source and heat sink	thermal	$0 = t_i^{b,set} - t_i^{b}$
Main heat source	hydraulic	$0 = p_1^{a,set} - p_1^a$
	hydraulic	$0 = p_1^{b,set} - p_1^{b}$
Additional heat source	thermal	$0 = \dot{Q}_i^{set} - \dot{Q}_i$
Heat sink	thermal	$0 = \dot{Q}_i^{set} - \dot{Q}_i$

4DH

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Solve the linear system for the unknown p, pa, pb, m and forward the variables to the next step.

environment

Solve the linear system for the unknown p, pa, pb, t, ta, tb, Q and forward results to the next step after calculating friction seperately.

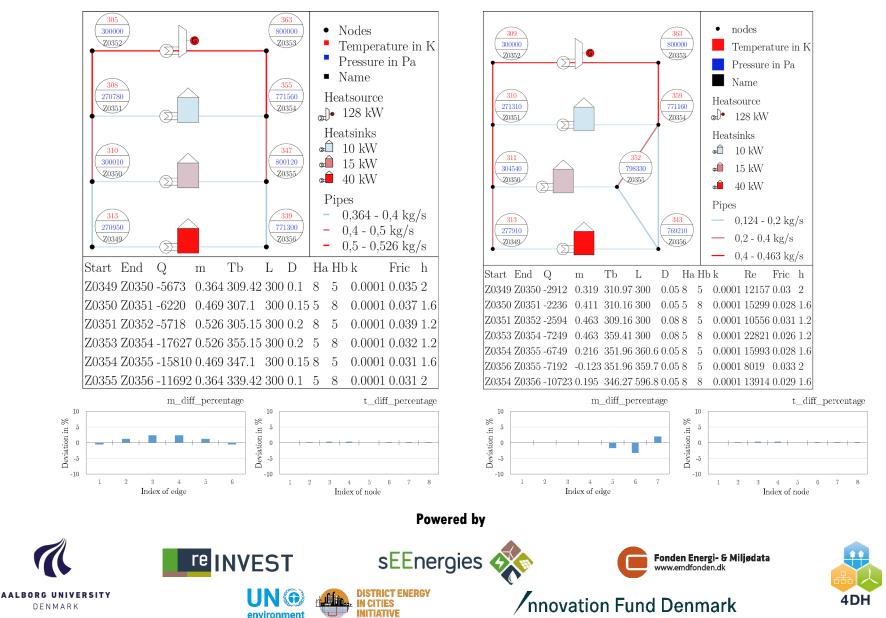
Using ipopt

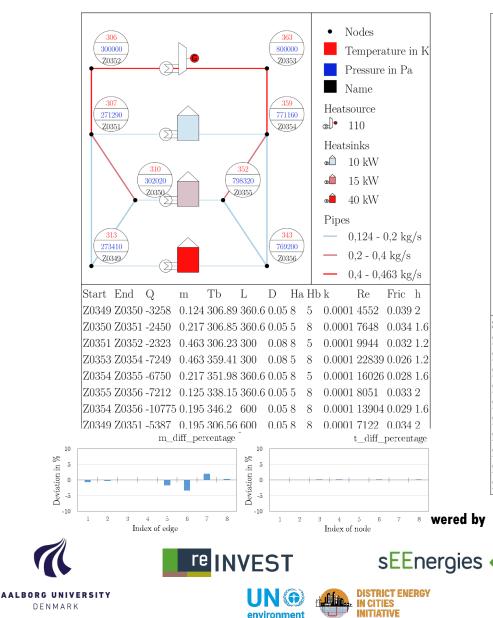
- right results -
- fast solving (from 5 min. _ down to 0.7 sec.)
- sparsity of matrices possible _

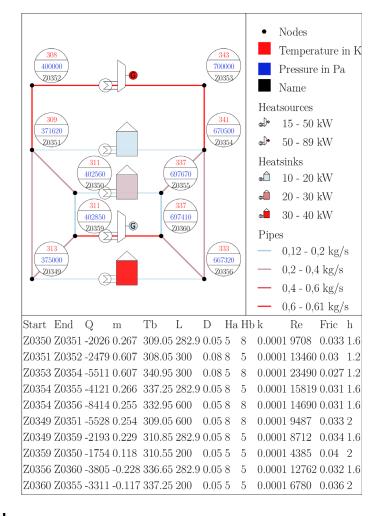


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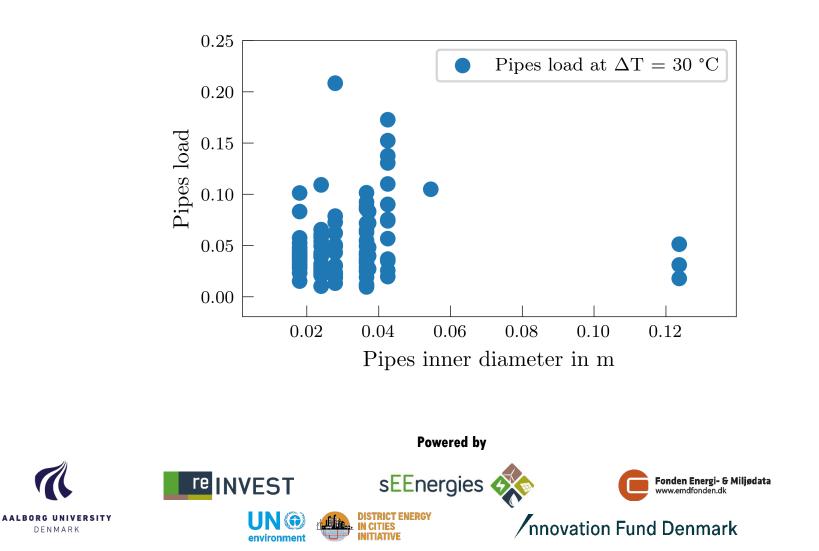




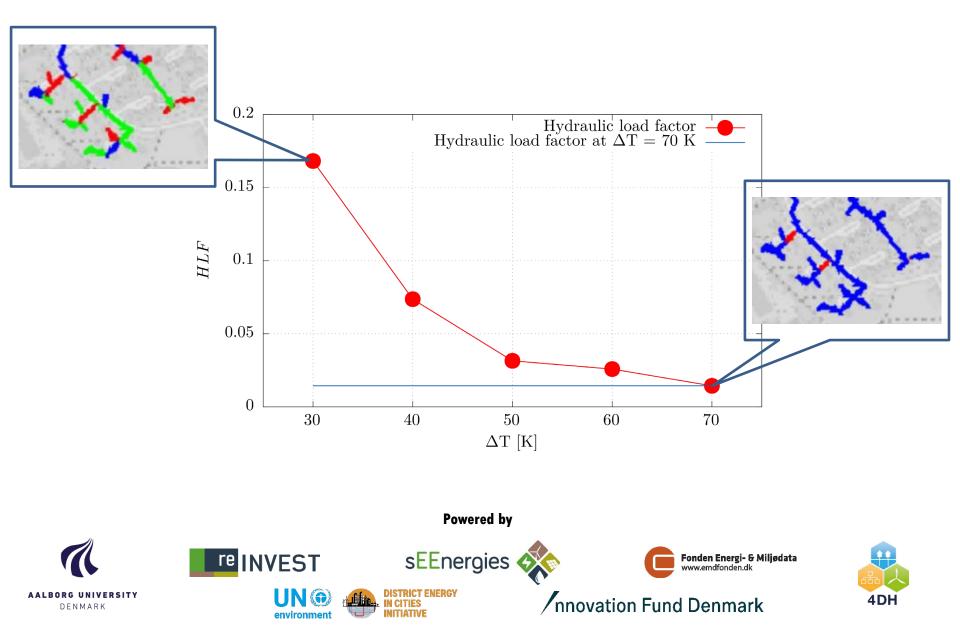


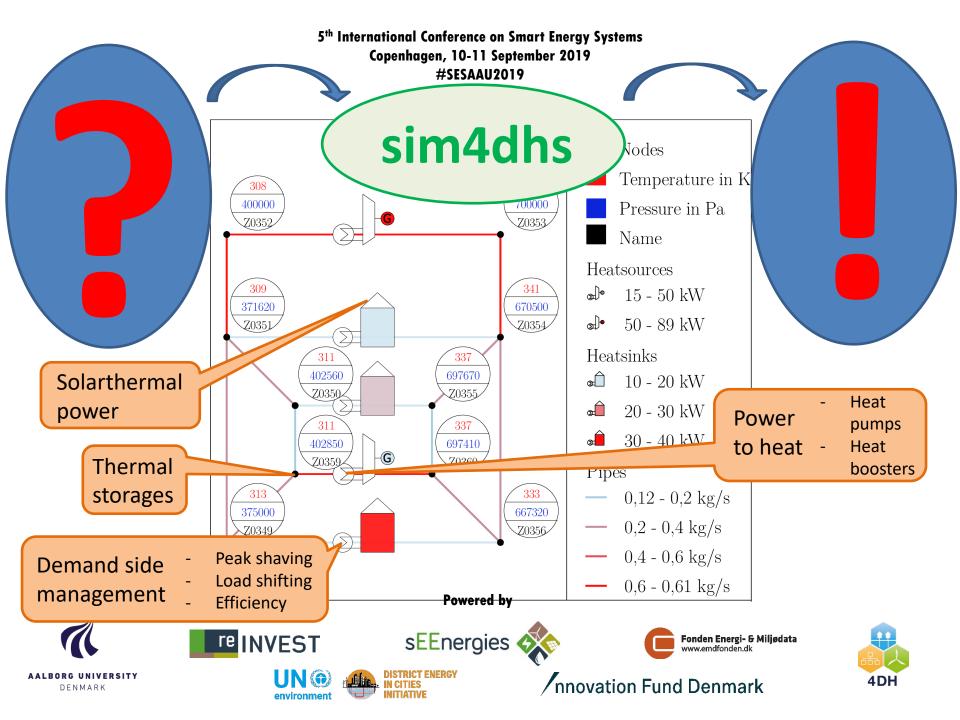
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Please feel free to ask any question!

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